

CERTAIN CONDITION OF SASAKIAN MANIFOLDS WITH QUARTER-SYMMETRIC NON-METRIC CONNECTION

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Abstract: The objective of this paper is to investigate the Sasakian manifolds with quarter-symmetric non-metric connection. We have investigate a Sasakian manifolds admitting the quarter-symmetric non-metric connections satisfying certain conditions. Further, we have proved that a Ricci soliton on a Sasakian manifold equipped with quarter-symmetric non-metric connection to be steady. We have also investigated ξ -conharmonically flat, Globally φ -conharmonically symmetric, η -parallel Ricci tensor and some interesting results. Finally, we have given an example of 3-dimensional Sasakian manifolds with respect to quarter-symmetric non-metric connection.

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1. Introduction

In 1950, an algebraic frame work for a connection as a differential operator was define by Koszul. Carton also characterised connection as a specific type of differential form. Torsion and curvature are two major components of an affine connection. On a Riemannian manifold, the concept of metric connection with torsion was introduced by Hayden [15]. In 1922, Agashe and Chafle [2] developed the concept of semi-symmetric non-metric connection. Golab [13] explored a quarter-symmetric connection in a differentiable manifold with affine connection. The quarter-symmetric non-metric connection is the most recognized connection and the study on Kenmotsu manifold with quarter-symmetric non-metric φ -connection was studied by several authors [3, 5, 11, 18, 20, 21].

The concept of contact geometry has involved for the mathematical formalism of classical mechanics [12]. Two important classes of contact manifolds are K-contact manifolds and Sasakian manifolds [4]. An odd dimensional analogue of Kaehler geometry is the Sasakian geometry. Sasakian manifolds were firstly studied by the famous geometer Sasaki [25] in 1960. Sasakian manifold have been studied by several authors [6, 8, 16, 19, 22, 24, 28]. Takahashi [29] introduced the notion of locally φ -symmetric Sasakian manifolds as a weaker version of local symmetry of such manifolds.

Adati and Motsumoto [1] defined para-Sasakian and special para-Sasakian manifolds which are considered as a special cases of an almost para contact manifold introduced by Sato and Matsumoto [26]. On a type of para-Sasakian manifolds have been studied by De and Tarafdar [9]. De and Guha [10] showed that an n -dimensional Weyl-semisymmetric para-Sasakian manifold is conformally flat. In [7], authors studied the properties of η -parallel Ricci tensor and provided several results. Analogous to the definition of η -parallelism given by Kon [17] on Sasakian manifolds.

Hamilton introduce the theory of Ricci flow to establish a canonical metric on a smooth manifold in 1982. The Ricci flow is an evolution equation for metrics on a Riemannian manifold is defined as follows:

$$\frac{\partial}{\partial t} g(t) = -R(t)g(t)$$

A Ricci soliton (g, V, λ) on a Riemannian manifold (M, g) is generalization of an Einstein metric such that it satisfies the following condition [14, 23]

$$L_V g + 2S + 2\lambda g = 0, \quad (1)$$

where S is the Ricci tensor, L_V is the Lie derivative operator along the vector field V on (M, g) and λ is a real number. The Ricci soliton is said to be shrinking, steady or expanding according as λ is negative, zero or positive.

The present work is organized as follows: In section-1 introduction is discussed. Section-2 is equipped with some prerequisites about Sasakian manifolds. Section-3, deals with Sasakian manifold admitting the quarter-symmetric non-metric connection (QSNMC) with some interesting results. Section-4 concerned with the study of Ricci soliton on a Sasakian manifold admitting the QSNMC. In section-5, we study the ξ -conharmonically flat Sasakian manifold admitting the QSNMC. Section-6 is devoted to the study of Globally φ -conharmonically symmetric Sasakian manifold with respect to the connection $\tilde{\nabla}$. In section-7, we study the η -parallel Ricci tensor admitting the QSNMC. In the last section, we have given an example of 3-dimensional Sasakian manifold in the support of our results.

2. Preliminaries

An $(2n + 1)$ -dimensional smooth manifold M together with a $(1,1)$ -tensor field φ , a vector field ξ , η is 1-form and Riemannian metric g is called an almost contact metric manifold if

$$\varphi^2(X) = -X + \eta(X)\xi, \quad (2)$$

$$\eta(\xi) = 1, \quad \varphi \xi = 0, \quad \eta(\varphi X) = 0, \quad (3)$$

$$g(\varphi X, \varphi Y) = g(X, Y) - \eta(X)\eta(Y), \quad g(X, \xi) = \eta(X), \quad g(\varphi X, Y) = -g(X, \varphi Y). \quad (4)$$

$$(\nabla_X \varphi)Y = g(X, Y)\xi - \eta(Y)X, \quad (5)$$

where ∇ denotes the Riemannian connection of g , then manifold $(M, \varphi, \xi, \eta, g)$ is called a Sasakian manifold. It can be shown that

$$(\nabla_X \eta)Y = g(X, Y) - \eta(X)\eta(Y), \tag{6}$$

$$(\nabla_X \xi) = -\varphi(X). \tag{7}$$

In a Sasakian manifold, we have [4]

$$R(X, Y)\xi = \eta(Y)X - \eta(X)Y, \tag{8}$$

$$R(\xi, Y)X = g(X, Y)\xi - \eta(X)Y, \tag{9}$$

$$R(\xi, X)\xi = \eta(X)\xi - X, \tag{10}$$

$$S(X, \xi) = 2n\eta(X), \tag{11}$$

$$Q\xi = 2n\xi, \tag{12}$$

$$S(\varphi X, \varphi Y) = S(X, Y) - 2n\eta(X)\eta(Y), \tag{13}$$

for any vector fields X, Y, Z on M , where R is the Riemannian curvature tensor, S is the Ricci tensor and Q is the Ricci operator.

The notion of η -parallelism on a Sasakian manifold was introduced by Kon [17]. A Ricci tensor S of an n -dimensional Kenmotsu manifold M is said to be η -parallel if it satisfies the tensorial relation

$$(\nabla_X S)(\varphi Y, \varphi Z) = 0, \tag{14}$$

for all X, Y, Z in $\chi(M)$.

3. Quarter-Symmetric Non-Metric Connection (QSNMC)

Let M be a Sasakian manifold with Levi-Civita connection ∇ . We define a linear connection $\tilde{\nabla}$ on M [30] as

$$\tilde{\nabla}_X Y = \nabla_X Y + \eta(Y)\varphi X. \tag{15}$$

Then a linear connection $\tilde{\nabla}$ is said to be a QSNMC if the torsion tensor \tilde{T} with respect to connection $\tilde{\nabla}$ satisfy

$$\tilde{T}(X, Y) = \eta(Y)\varphi X - \eta(X)\varphi Y, \tag{16}$$

where linear connection $\tilde{\nabla}$ is said to be a non-metric connection if $\tilde{\nabla}_g \neq 0$.

Using (4), we have

$$(\tilde{\nabla}_X g)(Y, Z) = -[\eta(Y)g(\varphi X, Z) + \eta(Z)g(\varphi X, Y)] \neq 0. \tag{17}$$

A linear connection $\tilde{\nabla}$ is said to be a QSNMC, if satisfies (15), (16) and (17).

Now from equation (15), we have

$$(\tilde{\nabla}_X \varphi)Y = g(X, Y)\xi - \eta(X)\eta(Y)\xi, \tag{18}$$

$$(\tilde{\nabla}_X \eta)Y = (\nabla_X \eta)Y = g(X, \varphi Y), \quad (19)$$

$$(\tilde{\nabla}_X g)(Y, \varphi Z) = -\eta(Y)g(\varphi X, \varphi Z), \quad (20)$$

On replacing Y by ξ in (15), we have

$$\tilde{\nabla}_X \xi = 0. \quad (21)$$

Thus a relation between the curvature tensor \tilde{R} and R of M is given as :

$$\tilde{R}(X, Y)Z = R(X, Y)Z + g(X, \varphi Z)\varphi Y - g(Y, \varphi Z)\varphi X + \eta(X)\eta(Z)Y - \eta(Y)\eta(Z)X. \quad (22)$$

Also, from equation (18), we obtain

$$\tilde{S}(X, Y) = S(X, Y) + g(Y, Z) - (2n + 1)\eta(Y)\eta(Z), \quad (23)$$

$$\tilde{R}(\xi, X)Y = g(X, Y)\xi - \eta(X)\eta(Y)\xi, \quad (24)$$

$$\eta(\tilde{R}(X, Y)Z) = g(X, Z)\eta(Y) - g(Y, Z)\eta(X), \quad (25)$$

$$R(X, Y)\xi = 0. \quad (26)$$

Theorem 3.1. Every $(2n+1)$ -dimensional Sasakian manifold equipped with QSNMC is irregular with respect to QSNMC.

Now, from (23), we get

$$\tilde{S}(Y, \xi) = 0, \quad (27)$$

$$\tilde{Q}(X) = Q(X) + X - (2n + 1)\eta(Y)\xi, \quad (28)$$

$$\tilde{r} = r. \quad (29)$$

Theorem 3.2. In a Sasakian manifolds admitting QSNMC $\tilde{\nabla}$, the scalar curvature tensor is invariant with respect to ∇ and $\tilde{\nabla}$.

4. Ricci soliton on Sasakian manifolds equipped with the quarter-symmetric non-metric connection

Let (g, ξ, λ) be the Ricci soliton on Sasakian manifold admitting $\tilde{\nabla}$, then from (1), we have

$$(\tilde{L}_\xi g)(X, Y) + 2\tilde{S}(X, Y) + 2\lambda g(X, Y) = 0. \quad (30)$$

With the help of (3), (4), (7) and (15), we get

$$(\tilde{L}_\xi g)(X, Y) = 0. \quad (31)$$

Using (23) and (31) in (30), we obtain

$$S(X, Y) = -(1 + \lambda)g(X, Y) + (2n + 1)\eta(X)\eta(Y). \quad (32)$$

Putting $Y = \xi$ in (32) and (27), we get

$$\lambda = 0. \quad (33)$$

Hence, we have the following theorem:

Theorem 4.1. A Ricci soliton on a Sasakian manifold M with respect to QSNMC $\tilde{\nabla}$ is always steady.

Corollary 4.1. A Ricci soliton on an η -Einstein Sasakian manifold M in terms of QSNMC $\tilde{\nabla}$ is always steady.

Let (g, V, λ) be the Ricci soliton on a Sasakian manifold $M(\varphi, \xi, \eta, g)$ admitting QSNMC $\tilde{\nabla}$ such that V is pointwise collinear with ξ i.e. $V = b\xi$, where b is a function. Then (1) implies that

$$bg(\tilde{\nabla}_X \xi, Y) + (Xb)\eta(Y) + bg(X, \tilde{\nabla}_Y \xi) + (Yb)\eta(X) + 2\tilde{S}(X, Y) + 2\lambda g(X, Y) = 0. \quad (34)$$

Replacing Y by ξ in (34) and using (7), (15) in (27), we get

$$(Xb) + (\xi b)\eta(X) + 2\lambda\eta(X) = 0. \quad (35)$$

Again replacing X by ξ in (35), we have

$$\xi b = -\lambda. \quad (36)$$

By virtue of (35) and (36), takes the form

$$(db) = \lambda n. \quad (37)$$

Applying d on (37), we yield

$$\lambda = 0. \quad (38)$$

Consequently from (37) we obtain $db = 0$, i.e., b is constant.

Hence we have the following theorem:

Theorem 4.2. If (g, V, λ) be a Ricci soliton on a Sasakian manifold M in reference to QSNMC $\tilde{\nabla}$ such that $V = b\xi$, then V is a constant multiple of ξ and the Ricci soliton is always steady.

5. ξ -conharmonically flat Sasakian manifolds with respect to the quarter-symmetric non-metric connection $\tilde{\nabla}$

Definition 5.1. A rank tensor \tilde{C} that remains invariant under Conharmonic transformation for an $(2n + 1)$ -dimensional Riemannian manifold M is given as

$$\tilde{C}(X, Y)Z = \tilde{R}(X, Y)Z - \frac{1}{2n-1} [g(Y, Z)\tilde{Q}X - g(X, Z)\tilde{Q}Y + \tilde{S}(Y, Z)X - \tilde{S}(X, Z)Y]. \quad (39)$$

Where \tilde{R} and \tilde{S} are the curvature tensor and Ricci tensor equipped with QSNMC $\tilde{\nabla}$ respectively and $\tilde{S}(Y, Z) = g(\tilde{Q}Y, Z)$.

Using (22) in (39), we get

$$\begin{aligned} \tilde{C}(X, Y)Z &= R(X, Y)Z + g(X, \varphi Z)\varphi Y - g(Y, \varphi Z)\varphi X + \eta(X)\eta(Z)Y \\ &- \eta(Y)\eta(Z)X - \frac{1}{2n-1} [g(Y, Z)\tilde{Q}X - g(X, Z)\tilde{Q}Y + \tilde{S}(Y, Z)X - \tilde{S}(X, Z)Y]. \end{aligned} \quad (40)$$

Using equations (23) and (28) in (40), we have

$$\begin{aligned} \tilde{C}(X, Y)Z &= C(X, Y)Z + g(X, \varphi Z)\varphi Y - g(Y, \varphi Z)\varphi X \\ &- \frac{2}{2n-1}[g(Y, Z)X - g(X, Z)Y - \eta(X)\eta(Z)Y + \eta(Y)\eta(Z)X] \\ &- \frac{2n+1}{2n-1}[g(X, Z)\eta(Y)\xi - g(Y, Z)\eta(X)\xi], \end{aligned} \quad (41)$$

where

$$C(X, Y)Z = R(X, Y)Z - \frac{1}{2n-1}[g(Y, Z)QX - g(X, Z)QY + S(Y, Z)X - S(X, Z)Y]. \quad (42)$$

Putting $Z = \xi$ in (41) and using equations (3) and (4), it follows that

$$\tilde{C}(X, Y)\xi = C(X, Y)\xi - \frac{4}{2n-1}[\eta(Y)X - \eta(X)Y]. \quad (43)$$

Suppose X and Y are orthogonal to ξ , then (43) becomes

$$\tilde{C}(X, Y)\xi = C(X, Y)\xi. \quad (44)$$

In view of the above discussion we can state the following theorem:

Theorem 5.1. An $(2n + 1)$ -dimensional Sasakian manifold is ξ -conharmonically flat with respect to QSNMC $\tilde{\nabla}$ iff the manifold is also ξ -conharmonically flat with respect to the Levi-Civita connection ∇ provided the vector fields X and Y are horizontal vector fields.

6. Globally φ -conharmonically symmetric Sasakian manifolds equipped with the quarter-symmetric non-metric connection $\tilde{\nabla}$

Definition 6.1. A Sasakian manifold M with respect to QSNMC $\tilde{\nabla}$ is called to be globally φ -conharmonically symmetric if

$$\varphi^2((\nabla_W C)(X, Y)Z) = 0. \quad (45)$$

for all vector fields X, Y, Z, W in $\chi(M)$.

From equation (42), we have

$$\begin{aligned} \eta(C(X, Y)Z) &= g(X, Z)\eta(Y) - g(Y, Z)\eta(X) \\ &- \frac{1}{2n-1}[g(X, Z)\eta(QX) - g(X, Z)\eta(QY) + S(Y, Z)\eta(X) - S(X, Z)\eta(Y)]. \end{aligned} \quad (46)$$

Contracting (11) and $S(X, Y) = g(QX, Y)$, yields

$$\eta(QX) = 2n\eta(X). \quad (47)$$

Moreover, combining (15), (46) and (47) and taking X, Y, Z, W are orthogonal to ξ , it follows that

$$(\tilde{\nabla}_W C)(X, Y)Z = \tilde{\nabla}_W C(X, Y)Z - C(\tilde{\nabla}_W X, Y)Z - C(X, \tilde{\nabla}_W Y)Z - \tilde{C}(X, Y)\tilde{\nabla}_W Z$$

$$= (\nabla_W C)(X, Y)Z. \tag{48}$$

Taking covariant differentiation of (41) with respect to W and using (17), (18), (19), (20) and (48) also taking X, Y, Z, W orthogonal to ξ , we have

$$\begin{aligned} (\tilde{\nabla}_W \tilde{C})(X, Y)Z &= (\nabla_W C)(X, Y)Z + g(X, \varphi Z)g(Y, W)\xi - g(Y, \varphi Z)g(X, W)\xi \\ &- \frac{2n+1}{2n-1} [g(X, Z)g(W, \varphi Y)\xi + g(Y, Z)g(W, \varphi X)\xi]. \end{aligned} \tag{49}$$

Now, applying φ^2 on both sides of (49) and using (2), it follows that

$$\varphi^2 \left((\tilde{\nabla}_W \tilde{C})(X, Y)Z \right) = \varphi^2 ((\nabla_W C)(X, Y)Z). \tag{50}$$

Theorem 6.1. An $(2n + 1)$ -dimensional Sasakian manifold is globally φ -conharmonically symmetric with respect to QSNMC $\tilde{\nabla}$ iff the manifold is also globally φ -conharmonically symmetric with the Levi-Civita connection ∇ provided the vector fields X, Y, Z, W are orthogonal to ξ .

7. η -parallel Ricci tensor equipped with the quarter-symmetric non-metric connection $\tilde{\nabla}$

In this section, we study η -parallel Ricci tensor with respect to QSNMC $\tilde{\nabla}$.

Definition 7.1. A Ricci tensor \tilde{S} of an n -dimensional Kenmotsu manifold M endowed with a semi-symmetric non-metric connection $\tilde{\nabla}$ is said to be η -parallel for $\tilde{\nabla}$ if it satisfies the relation $(\tilde{\nabla}_X \tilde{S})(\varphi Y, \varphi Z) = 0$, for arbitrary vector fields X, Y and Z .

From (15), we have

$$\tilde{\nabla}_X(\tilde{Q}Y) = \nabla_X(\tilde{Q}Y) - \eta(\tilde{Q}Y)\varphi X. \tag{51}$$

With the help of (3), (6), (15) and (28), we find

$$\tilde{\nabla}_X(\tilde{Q}Y) = (\tilde{\nabla}_X \tilde{Q})Y + Q(\nabla_X Y) + \nabla_X Y - (2n + 1)\eta(\nabla_X Y)\xi + \eta(Y)Q(\varphi X) + \eta(Y)\varphi X, \tag{52}$$

and

$$\nabla_X(\tilde{Q}Y) = (\nabla_X Q)Y + Q(\nabla_X Y) + \nabla_X Y - (2n + 1)[g(X, \varphi Y)\xi + \eta(\nabla_X Y)\xi - \eta(Y)\varphi X]. \tag{53}$$

From the equation (52) and (53), we obtain

$$(\tilde{\nabla}_X \tilde{Q})Y = (\nabla_X Q)Y - \eta(Y)Q\varphi X - (2n + 1)g(X, \varphi Y)\xi - 2(2n + 1)\eta(Y)\varphi X. \tag{54}$$

In view of (3), (11) and $(\tilde{\nabla}_X \tilde{S})(Y, Z) = g((\tilde{\nabla}_X \tilde{Q})Y, Z)$, the above relation becomes

$$(\tilde{\nabla}_X \tilde{S})(Y, Z) = (\nabla_X S)(Y, Z) - \eta(Y)S(\varphi X, Z) - (2n + 1)[\eta(Z)g(X, \varphi Y) + \eta(Y)g(\varphi X, Z)]. \tag{55}$$

Replacing the vector fields Y by φY and Z by φZ in (55) and using (3), we find

$$(\tilde{\nabla}_X \tilde{S})(\varphi Y, \varphi Z) = (\nabla_X S)(\varphi Y, \varphi Z). \quad (56)$$

In view of (14), (56) and definition (7.1), we state the following:

Theorem 7.1. Let M be an $(2n + 1)$ -dimensional Sasakian manifold is equipped with a QSNMC $\tilde{\nabla}$, then the Ricci tensor \tilde{S} on M is η -parallel with respect to connection $\tilde{\nabla}$ iff the manifold has η -parallel Ricci tensor S for the Levi-Civita connection ∇ .

8. Example of Sasakian Manifolds.

Let $M = [(x, y, z) \text{ in } \mathfrak{R}^3 : (z) > 0]$ be a 3-dimensional manifold, where (x, y, z) are the standard coordinates in \mathfrak{R}^3 . Choosing vector fields [27]

$$e_1 = x \left(\frac{\partial}{\partial x} + \frac{\partial}{\partial y} \right) - 2y \frac{\partial}{\partial z}, e_2 = \frac{\partial}{\partial y}, e_3 = \frac{\partial}{\partial z} = \xi,$$

are linearly independent at every point of M .

The Riemannian metric g is defined by

$$\begin{aligned} g(e_1, e_2) &= g(e_2, e_3) = g(e_3, e_1) = 0, \\ g(e_1, e_1) &= g(e_2, e_2) = g(e_3, e_3) = 1. \end{aligned} \quad (57)$$

Suppose η be the 1-form defined as $\eta(X) = g(X, \xi)$.

Let φ be the (1,1)-tensor field defined by

$$\varphi(e_1) = e_2, \varphi(e_2) = -e_1, \varphi(e_3) = 0. \quad (58)$$

By linearity property of φ and g , we have

$$\eta(e_3) = \eta(\xi), \quad \varphi^2 X = -X + \eta(X)e_3, \quad g(\varphi X, \varphi Y) = g(X, Y) - \eta(X)\eta(Y),$$

Consider ∇ be the Levi-Civita connection with Riemannian metric g , then we have

$$[e_1, e_2] = 2e_3, \quad [e_1, e_3] = 0, \quad [e_2, e_3] = 0. \quad (59)$$

Koszul's formula is given as

$$\begin{aligned} 2g(\nabla_X Y, Z) &= Xg(Y, Z) + Yg(Z, X) - Zg(X, Y) \\ &+ g([X, Y], Z) - g([Y, Z], X) + g([Z, X], Y). \end{aligned} \quad (60)$$

for arbitrary vector fields X, Y, Z in $\chi(M)$.

By virtue of (60), we have

$$\begin{aligned} \nabla_{e_1} e_1 &= 0, \quad \nabla_{e_1} e_2 = e_3, \quad \nabla_{e_1} e_3 = -e_2, \quad \nabla_{e_2} e_1 = -e_3, \quad \nabla_{e_2} e_2 = 0, \\ \nabla_{e_2} e_3 &= e_1, \quad \nabla_{e_3} e_1 = -e_2, \quad \nabla_{e_3} e_2 = e_1, \quad \nabla_{e_3} e_3 = 0. \end{aligned} \quad (61)$$

Let us take a vector field $X = X^1 e_1 + X^2 e_2 + X^3 e_3$ and the structure vector field $\xi = e_3$, then we have

$$\tilde{\nabla}_X \xi = -X^1 e_2 + X^2 e_1, \tag{62}$$

and

$$\nabla_X \xi = -\varphi X = -X^1 e_2 + X^2 e_1, \tag{63}$$

where X^1, X^2, X^3 are scalars.

Hence for $\xi=e_3$ the manifold $(M, \varphi, \xi, \eta, g)$ under consideration example is a Sasakian manifolds.

By virtue of (3), (15), (58) and (61), we have

$$\begin{aligned} \tilde{\nabla}_{e_1} e_1 = 0, \tilde{\nabla}_{e_1} e_2 = e_3, \tilde{\nabla}_{e_1} e_3 = 0, \tilde{\nabla}_{e_2} e_1 = -e_3, \tilde{\nabla}_{e_2} e_2 = 0, \\ \tilde{\nabla}_{e_2} e_3 = 0, \tilde{\nabla}_{e_3} e_1 = -e_2, \tilde{\nabla}_{e_3} e_2 = e_1, \tilde{\nabla}_{e_3} e_3 = 0. \end{aligned} \tag{64}$$

In view of (16), the torsion tensor \tilde{T} with respect to $\tilde{\nabla}$ as follows:

$$\tilde{T}(e_i, e_j) = 1,2,3. \tilde{T}(e_1, e_3) = e_2 \neq 0, \tilde{T}(e_2, e_3) = -e_1 \neq 0.$$

Also we have

$$(\tilde{\nabla}_{e_1}, g)(e_2, e_3) = -1 \neq 0,$$

Hence the manifold is a Sasakian manifold with respect to the connection $\tilde{\nabla}$.

The curvature tensor $(e_i, e_j)e_k ; i, j, k = 1, 2, 3$ of ∇ can be calculated as follows:

$$\begin{aligned} R(e_1, e_2)e_3 = 0, R(e_1, e_3)e_3 = e_1, R(e_2, e_3)e_2 = -e_3, \\ R(e_3, e_1)e_1 = e_3, R(e_2, e_1)e_1 = -3e_2, R(e_2, e_3)e_3 = -e_2, \\ R(e_2, e_3)e_1 = 0, R(e_1, e_2)e_2 = -3e_1, R(e_3, e_1)e_2 = 0. \end{aligned} \tag{65}$$

Along with $R(e_i, e_i) e_i = 0; \forall i = 1, 2, 3$.

From the above calculation, we also calculate

$$\begin{aligned} \tilde{R}(e_1, e_2)e_3 = 0, \tilde{R}(e_1, e_3)e_3 = 0, \tilde{R}(e_2, e_3)e_2 = -e_3, \\ \tilde{R}(e_3, e_1)e_1 = e_3, \tilde{R}(e_2, e_1)e_1 = -2e_2, \tilde{R}(e_2, e_3)e_3 = 0, \\ \tilde{R}(e_2, e_3)e_1 = 0, \tilde{R}(e_1, e_2)e_2 = 0, \tilde{R}(e_3, e_1)e_2 = 0. \end{aligned} \tag{66}$$

Along with $\tilde{R}(e_i, e_i) e_i = 0; \forall i = 1, 2, 3$.

The Ricci tensor $S(e_j, e_k); \forall j, k = 1, 2, 3$ of ∇ is given by using (65) in the equation

$$S(e_j, e_k) = \sum_{i=1}^3 g(R(e_i, e_j)e_k, e_i).$$

It follows that :

$$S(e_1, e_1) = -2, S(e_2, e_2) = -2, S(e_3, e_3) = -1. \tag{67}$$

The $\tilde{S}(e_j, e_k); \forall j, k = 1, 2, 3$ of $\tilde{\nabla}$ can also be calculated by using (66) in the equation :

$$\tilde{S}(e_j, e_k) = \sum_{i=1}^3 g(\tilde{R}(e_i, e_j)e_k, e_i).$$

It follows that :

$$\tilde{S}(e_1, e_1) = -1, \tilde{S}(e_2, e_2) = 1, \tilde{S}(e_3, e_3) = 0. \quad (68)$$

Along with $\tilde{S}(e_j, e_k) = 0; \forall j, k = 1, 2, 3 (j \neq k)$.

By virtue of (33) and (67), we have

$$\lambda = 0. \quad (69)$$

Thus the Ricci soliton (g, ξ, λ) on manifold admitting the connection $\tilde{\nabla}$ is always steady. Hence theorem (4.1) is verified.

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